



Couplings

F A C E Ø40R 10*10
 F A C H - S Ø32 6*8 - LK

| F | A | C | E | | Ø40R | 10*10 | Custom Made |
|-------------------------|--|---|--|-----------------------------------|---|---|-------------|
| F | A | C | H | S | Ø32 | 6*8 | |
| Type | Material | Axis Fixing | Coupling Model | Length | O.D. / (Jaw Type Option) | Ød1*Ød2 | Key way |
| F: Flexible R: Rigid | A: Aluminum S: Stainless Steel C: Carbon steel | M: Set screw fixing C: Clamping fixing B: 2 Pieces S: Zero backlash type | S: Spiral beam type(for servo motor) M: Spiral beam type (for stepping motor) C: Metal disk with high rigid design H: Metal disk in straight type T: Metal disk in steps type B: Bellows design G: Oldham type - phosphor bronze spacer P: Oldham type - carbon resin spacer J: Oldham type - Black POM spacer N: Oldham type - POM spacer E: Jaw type U: Aluminum spacer | L: Long design S: Short design | ◆ Refer to dimension table to decide the O.D. ◆ Jaw Spider options: B: Blue (80 ShoreA) W: White (92 ShoreA) R: Red (98 ShoreA) | ◆ Bore diameter of two sides of the coupling ◆ LK: left side Ød1 ◆ RK: right side Ød2 ◆ WK: Both sides (Ød1 & Ød2) | |

Note : ◆ Material AL, surface in anodized finished.

- ◆ Accessories are clamping screws and set screws.
- ◆ Shaft dia. Ød1, Ød2 accepted by custom sizes.(Within specified Max. bore dimensions)
- ◆ GMT coupling series are all processed in cryogenic treatment.(Refer to P.0453)

- ◆ Coupling is a mechanism device, connecting transmission between two shafts and transmitting safety torque.
- ◆ Coupling divided into "Flexible type" and "Rigidity type".
- ◆ To apply flexible couplings timing in case of power transmission, two shafts are not easy to set in alignment, or to simplify two shafts installation. It contains shock buffer to absorb parallelism, deflection, axial displacement, deviation improvement, and improvement of traditional transmission power, so few deviation would not cause any unusual situation on bearing. It's widely applied to current markets.
- ◆ Rigidity coupling is an unit causing non-eccentric, non-deflection, and make two connected shafts fixed in one unit. Users must do the best to have motor running and axis of load in alignment due to high requirement of concentricity, also means of axis has to be calibrated strictly; otherwise, the rotating shaft would be broken caused by mechanism fatigue, also the bearing would be thermal abrasion due to eccentric load, those were brought by continuous vibration of the axis during long term running of the motor. The advantage of rigidity coupling is to transmit transmission torque precisely.



(1) There are five ways to fix coupling onto shaft as below. Please select coupling as your demand.

(2) Set screw or clamping screw (hexagonal countersink screw) shall be secured by screw driver or torque wrench. Securing torque refer to product specifications.



Set Screw Fixing

This fixing is low cost is the most traditional.

Front of screw contacting with shaft directly may cause damage or difficult disassembly.



Clamping Fixing

Use sink screw securing to narrow the slit for clamping shaft tightly.

Clamped fix and easy disassembly won't cause damage of shaft.



Separation Fixing

Use separated bushings to fix and disassemble without moving your equipment.



Key Way Fixing

This type is also traditional, like set screw fixing, suits for transmission in higher torque. Prevent from parallel movement, it's usually used with set screw fixing and clamp fixing together.

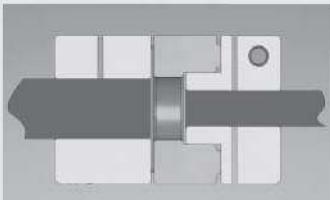


Zero Backlash Type

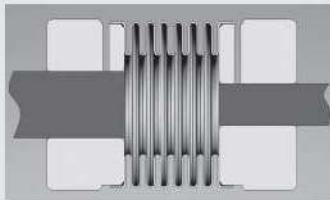
Zero backlash type coupling is designed to be equipped high precision clamping nut as one unit, performs high friction moment and reliable movement which is suitable for spindle transmission of the machine.

To maintain installation completeness of all kinds of couplings, it's recommended to install as follow charts to avoid direct contact of two shafts and to have a regular run.

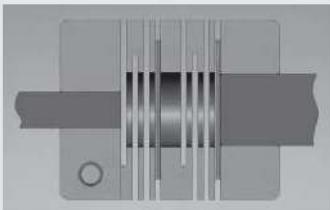
Oldham Type



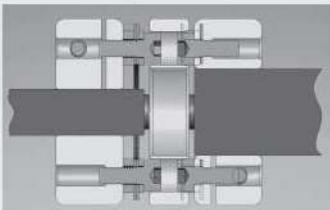
Bellows Type



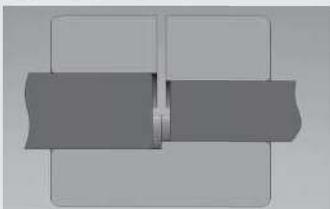
Spiral Beam Type



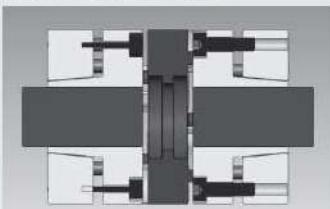
Metal Disk Type



Rigidity Coupling



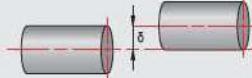
Zero Backlash Type



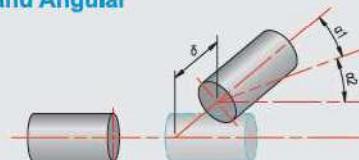
Coupling - Deviation Adjustment

- (1) Flexible coupling transmits torque and rotation angle, and absorb deviation from shaft installation. It may cause vibration or shortening life hours of coupling, while deviation is over allowed range. Thus, make sure and take perfect adjustment for deviation.
- (2) There are three deviation for shaft, as parallel deviation, angular deviation and axial deviation. Please adjust deviation lower than allowed range listed in the product spec offered by our catalog.
- (3) The max. allowable deviation listed in our catalog is in case of only one deviation existing. While two or more deviation existing at same time, allowable range shall be lower than $1/2 \times$ max. deviation listed in the spec of catalog.
- (4) Deviation happened not only on equipment installation, but caused by vibration in running progress, heated expansion, bearing abrasion. Thus, it's recommended to adjust axial deviation lower than $1/3 \times$ Max. range.

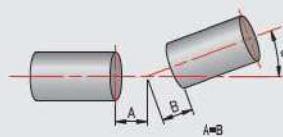
Parallel Deviation



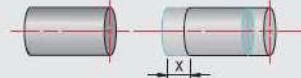
Complex Deviation in Parallel and Angular



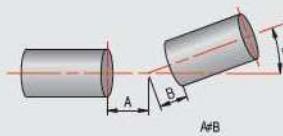
Symmetry Angular Deviation



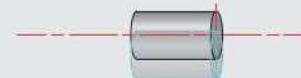
Axial Deviation



Asymmetry Angular Deviation



Run Out



Torque

In physics, torque is defined as "force in vertical" x "distance to rotating center", metric unit (N·m), divided by acceleration of gravity 9.8m / sec², unit could be converted to familiar (kg·m). Imperial unit lb·ft, in case of conversion to metric unit, just take lb·ft divided by 7.22. Torque we called is not force unit, but a kind of the moment of force, which means capacity of energy transforming. We could see the connection from normal unit used in calculating torque (Kgm), and generally judging from words: Kgm stands for the capacity of rising an object weighed 1 kg in 1 meter movement. This is a kind of the moment of force, so inappropriate to call it force. Motor producing force per time unit is decided by RPM and torque of motor, and REC out shown in motor, (W) shown in Japan, (HP) power output shown in USA and Europe.
(1HP=746w=0.746kw)

Coupling - Allowed Torque

Transmitted torque occurs in allowed speed range rotating continuously.

Max. Torque in Driven Side

Max. torque in driven side being hit in the moment, ex: torque produced while breaking.

Allowable Angular (Deflection)

The deflection between two shafts while connecting two shafts.

Allowable Axial Deviation Displacement

Displacement caused in axial while connecting two shafts.

Inertial Torque

It's not easy to change running status of object with big mass (whether from static to running or running to static); equally, rotating inertial or inertial torque is to show keeping object in running status, bigger inertia torque makes tough rotation.

Static Torsional Stiffness

Required (N·m) to rotate 1 radian.

Motor

Induction Motor

- (1) More than triple torque occurs in case of running momentarily.
- (2) Shaft axis center of the motor has $\pm 1.5\text{mm}$ movement back and forth while running, and it's not recommended to use spiral beam type.
- (3) DC motor could be used in working environment with dust.

Stepping Motor

- (1) Without triple torque in case of running momentarily, but max. rated torque of motor occurs.
- (2) Larger torque in low speed than servo motor in same level.
- (3) Higher RPM, smaller torque in motor.
- (4) Motor have temperature rise in case of running continuously. (to improve by using disk type coupling)
※ Force output in stepping motor is smaller than servo motor.

Servo Motor

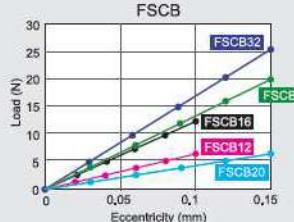
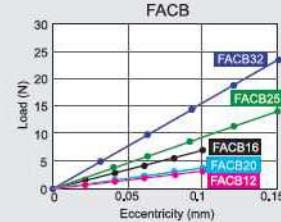
- (1) More than triple torque occurs in case of running momentarily.
- (2) Under rated RPM range, cause rated torque.
- (3) Same torque produce in low speed and high speed
- (4) Temperature rise is small in case of running continuously.

Encoder

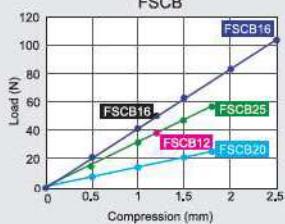
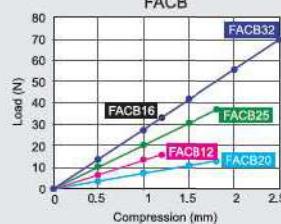
- (1) Built-in in servo motor, has tiny driven torque.
- (2) Or connected to stepping motor. (optional)

Bellows type - Rigidity Standard

Eccentric Reaction Force



Thrust Reaction Force



Spiral Beam Type - Rigidity Standard



FAMML



FAMMS



FACML



FACMS



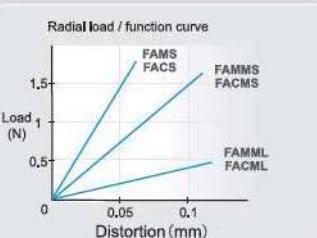
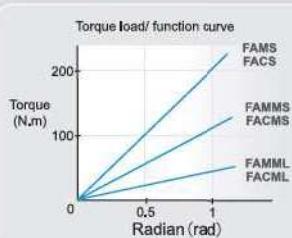
FAMS

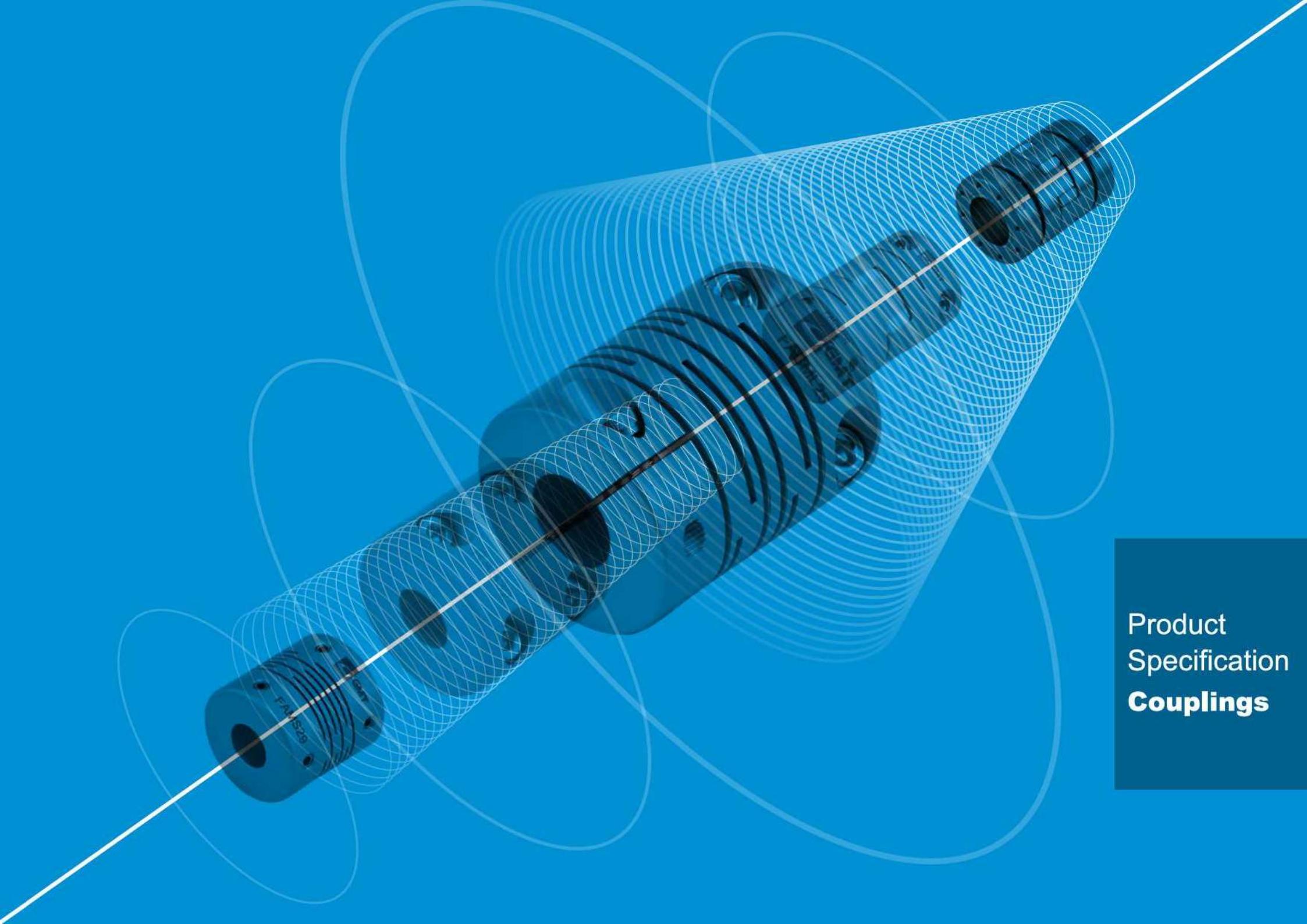


FACS

Torque rigidity and flexibility - Balance acquired among incompatible functions. These flexible couplings apply to stepping motor.

Character Comparison



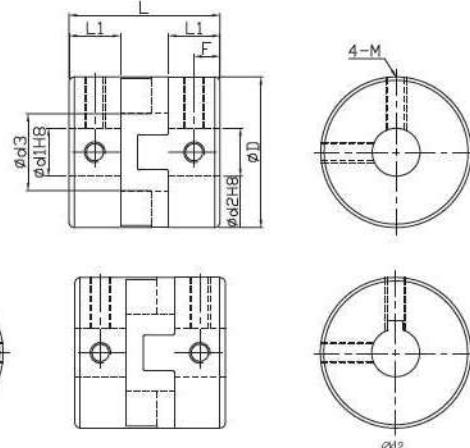


Product
Specification
Couplings

FAMJ



- Operating temperature : -20°C~80°C
- Offset of angular, parallel, or axial deviation are individual allowed value, so couple reasons of axial offset appearing at same time would reduce the unit allowable value.
- Available options for key way per inner diameter is bigger than 6mm. (Refer to page 39)



FAMJL_K(key way Ød1 side)
FAMJR_K (key way Ød2 side)
FAMJWK (key way Ød1 and Ød2 side)

| Component | Material | Surface Finish | Accessories |
|------------|----------------|----------------|-------------|
| Main frame | Aluminum Alloy | Anodized | |
| Spacer | Black (POM) | — | Set screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | | | | | Ød3 | L | L1 | F | Set screw M Lock torque (N·m) | | | |
|------------|----|------------------------------|----|----|----|----|----|----|----|----|----|-----|----|------|----|--|-----|------|------|
| Model No. | ØD | 14 | 15 | 16 | 18 | 20 | 22 | 25 | 26 | 28 | 30 | 35 | 38 | | | | | | |
| FAMJ | 44 | ● | ● | ● | ● | ● | ● | | | | | | | 22.5 | 46 | 15 | 7.5 | 6 | 7.0 |
| | 55 | | | | ● | ● | ● | ● | ● | | | | | 28 | 57 | 19 | 9.5 | 8 | 15.0 |
| | 70 | | | | | | ● | ● | ● | ● | ● | ● | 39 | 77 | 25 | 12.5 | 10 | 30.0 | |

* Moment of inertial| torque and weight calculated by maximum diameter.

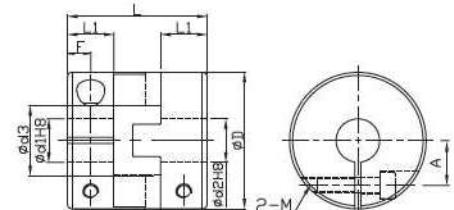
| Specification | Allowable Wrench Torque (N·m) | Allowable Misalignment | | Static Torsional Stiffness (N·m·rad) | Max. RPM (r/min ⁻¹) | ★ Moment of Inertia (kg·m ²) | ★ Weight (g) | |
|---------------|-------------------------------|------------------------|---|--------------------------------------|---------------------------------|--|---------------------|-----|
| FAMJ | 44 | 30 | 2 | 1 | 1500 | 12000 | 4*10 ⁻⁵ | 140 |
| | 55 | 45 | | 1.5 | 2800 | 10000 | 11*10 ⁻⁵ | 260 |
| | 70 | 80 | | 2 | 4800 | 8000 | 40*10 ⁻⁵ | 450 |

Ordering Example: FAMJ44 - 18 Ød1 * 18 Ød2 100 PCS
Model no. Ød1 Ød2 Qty

FACJ



- Operating temperature : -20°C~80°C
- Offset of angular, parallel, or axial deviation are individual allowed value, so couple reasons of axial offset appearing at same time would reduce the unit allowable value.
- Select bigger lock torque of clamping screw than listed values on catalogs when shaft diameter is too small.
- List torque tightness values are only for general standard.
- Available options for key way per inner diameter is bigger than 6mm. (Refer to page 39)



FACJLK (key way Ød1 side)
FACJRK (key way Ød2 side)
FACJWK(key way Ød1 and Ød2 side)

| Component | Material | Surface Finish | Accessories |
|------------|----------------|----------------|----------------|
| Main frame | Aluminum Alloy | Anodized | |
| Spacer | Black (POM) | — | Clamping screw |

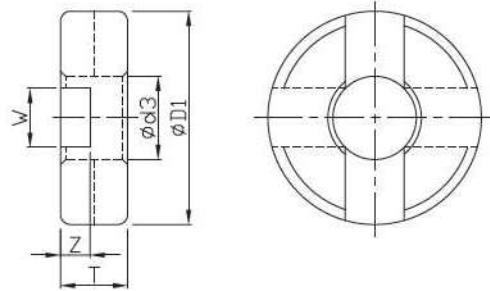
| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | | | | | Ød3 | L | L1 | F | A | Clamping screw M Lock torque (N·m) | |
|------------|----|------------------------------|----|----|----|----|----|----|----|----|----|-----|------|----|------|-----|---|---------|
| Model No. | ØD | 14 | 15 | 16 | 18 | 20 | 22 | 25 | 28 | 30 | 35 | | | | | | | |
| FACJ | 44 | ● | ● | ● | ● | ● | ● | | | | | | 22.5 | 46 | 15 | 7.5 | 14.5 | 5 *8.4 |
| | 55 | | | | ● | ● | ● | ● | | | | | 28 | 57 | 19 | 9.5 | 17 | 6 *14.4 |
| | 70 | | | | | ● | ● | ● | ● | ● | ● | 39 | 77 | 25 | 12.5 | 24 | 8 *30.0 | |

* Moment of inertial| torque and weight calculated by maximum diameter.

| Specification | Allowable Wrench Torque (N·m) | Allowable Misalignment | | Static Torsional Stiffness (N·m·rad) | Max. RPM (r/min ⁻¹) | ★ Moment of Inertia (kg·m ²) | ★ Weight (g) | |
|---------------|-------------------------------|------------------------|---|--------------------------------------|---------------------------------|--|---------------------|-----|
| FACJ | 44 | 26 | 2 | 1 | 1500 | 12000 | 4*10 ⁻⁵ | 140 |
| | 55 | 40 | | 1.5 | 2800 | 10000 | 11*10 ⁻⁵ | 260 |
| | 70 | 72 | | 2 | 4800 | 8000 | 40*10 ⁻⁵ | 450 |

©FAMJ&FACJ spacer selection, please refer to P.43

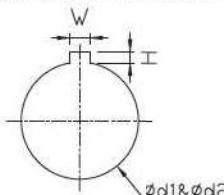
Ordering Example: FACJ44 - 16 Ød1 * 18 Ød2 100 PCS
Model no. Ød1 Ød2 Qty

FS-PC

◆ Spacer

Material : carbon resin

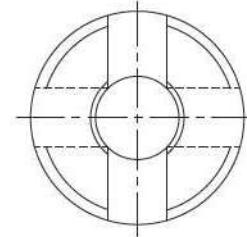
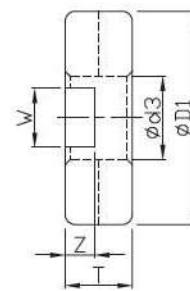
| Dimensions | | ØD1 | T | Ød3 | W | Z | Coupling |
|------------|----|------|-----|------|-----|-----|------------------|
| Model No. | ØD | | | | | | |
| FS-PC | 6 | 6.2 | 2.2 | 2.4 | 1.3 | 1.3 | FSMP6 |
| | 8 | 8.2 | 2.4 | 3.4 | 1.6 | 1.5 | FSMP8 |
| | 10 | 10.2 | 2.6 | 4.4 | 1.6 | 1.6 | FSMP10 |
| | 12 | 12.5 | 3.8 | 4.0 | 3 | 1.8 | FSMP12 |
| | 15 | 15 | 4.8 | 5.0 | 3.4 | 2.3 | FSMP15 FSCP15 |
| | 17 | 17.5 | 6 | 7.2 | 4.6 | 2.9 | FSMP17 FSCP17 |
| | 20 | 21 | 6.6 | 8.2 | 5.8 | 3.2 | FSMP20 FSCP20 |
| | 26 | 27 | 7 | 12.0 | 7 | 4 | FSMP26 FSCP26 |
| | 30 | 31 | 8.5 | 13.0 | 7 | 4 | FSMP30 FSCP30 |
| | 34 | 35 | 7 | 13.0 | 7 | 4 | FSMP34 FSCP34 |
| | 38 | 41 | 9.5 | 16.0 | 7 | 4 | FSMP38 FSCP38 |

◆ W dimension is made in strict standard, and inter-inland adjustment,

 Ordering Example: FS-PC
Model no. 26
ØD

◆ Key way dimensions

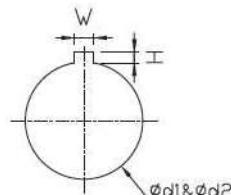
(Reference for FSMG, FSCG, FSMP, FSCP)

| Shaft dia. Ød1 □ Ød2 | W | | H | | Key dimensions W*H |
|-------------------------|-----------------|---------------------|-----------------|---------------------|--------------------|
| | Datum dimension | Allowable tolerance | Datum dimension | Allowable tolerance | |
| 6~7.9 | 2 | ±0.0125 | 1.0 | | 2*2 |
| 8~10 | 3 | | 1.4 | | 3*3 |
| 10.1~12 | 4 | | 1.8 | +0.1 | 4*4 |
| 12.1~17 | 5 | ±0.0150 | 2.3 | 0 | 5*5 |
| 17.1~20 | 6 | | 2.8 | | 6*6 |

FS-PP

◆ Spacer

Material : Polyacetal (POM)

| Dimensions | | ØD1 | T | Ød3 | W | Z | Coupling |
|------------|----|------|----|------|------|------|------------------|
| Model No. | ØD | | | | | | |
| FS-PP | 44 | 44.3 | 14 | 22.5 | 10.4 | 9 | FAMJ44 FACJ44 |
| | 55 | 55 | 17 | 28 | 13 | 11 | FAMJ55 FACJ55 |
| | 70 | 69 | 25 | 39 | 15 | 16.5 | FAMJ70 FACJ70 |

 Ordering Example: FS-PP
Model no. 44
ØD

◆ Key way dimensions

(Reference for FAMJ, FACJ)

| Shaft dia. Ød1 □ Ød2 | W | | H | | Key dimensions W*H |
|-------------------------|-----------------|---------------------|-----------------|---------------------|--------------------|
| | Datum dimension | Allowable tolerance | Datum dimension | Allowable tolerance | |
| 14~17 | 5 | ±0.0150 | 2.3 | +0.1 | 5*5 |
| 17.1~22 | 6 | | 2.8 | 0 | 6*6 |
| 22.1~30 | 8 | ±0.0180 | 3.3 | +0.2 | 8*7 |
| 30.1~38 | 10 | | | 0 | 10*8 |

Polyacetal plastic(POM)

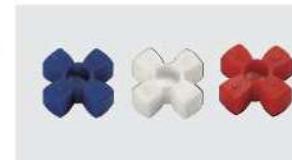
Polyacetal(Abrv. POM), also called Plastic steel.

POM character : Polyoxymethylene is a kind of thermal plasticity polymer, having good physical, mechanical and chemical functions. It has high hardness, rigidity in very wide range of temperature. Secondly, resisted strength, fatigue resistance, creep resistance are excellent as well, especially outstanding dimension stability and durability; besides, polyoxymethylene has advantages of small friction factor, good durability, dispensable lubricant, good organic solvent-resistance, low absorbent ability etc.... Long-term using in the range of -40~104°C. In addition, polyoxymethylene has better corrosion resistance.


Urethane(PU)

PU glue is also called polyurethane

Polyurethane application is kind of flexible polymer, used as elastic resilience and damping in shock absorber. Generally, polyurethane suits for terrains with collision from small to medium level most, and adjustable polyurethane makes perfect effect. Urethane glue is water-resistant, abrasion-resist, high mechanism strength, and product hardness adjusted by purposes, high elasticity, good shock absorability, no hurting machine tools, a excellent anti-collision material.


Highly wear-resisting copper alloy

Highly wear-resisting copper alloy(aluminum bronze(C6161))

High tensile-resist strength, wear-resistance, and offer various extruded materials, forged materials, centrifugal rolls, and applied to gear, bearing, bushing, slide panel, plastic mould, electrode heads....etc.


Character chart for plastic material

| Material | Specific gravity | Thermal distortion temperature | Flammability | Feature | | Purpose |
|----------|------------------|--------------------------------|--------------|---|---|---|
| | | | | Advantage | Defect | |
| POM | 1.14 ~ 1.43 | Homopolymer | Flammable | 1. Tough & flexible | 1. Low anti-ultraviolet | 1. Parts in industry load |
| | | | | 2. CIP character · excellent fatigue resistance | 2. Heat dissolution and formaldehyde gas produced | 2. Automobile · electric parts |
| | | | | 3. Self-lubricity, low abrasion-resistance | 3. Low anti-acid | 3. Toy parts |
| | | | | 4. Drug tolerance | | 4. Substitute for metal |
| | | | | 5. Good heat-resistance | | |
| PU | 1.11 ~ 1.24 | Softening point | Flammable | 1. Good abrasion-resistance | 1. Softness in low level · easily stuck while demolding and shrink. | 1. Shoes and sports utilities |
| | | | | 2. Climate-resistant and low temperature-resistant (-25°C~60°C) | 2. Long dried time for materials | 2. Shock absorb, noise elimination, bushing |
| | | | | 3. anti-oxygen, ozone aging characters | | 3. Grip and grasp with soft-touch feeling |
| | | | | 4. Good tensile rate of bending strength | | |
| | | | | 5. Adjustable toughness | | |

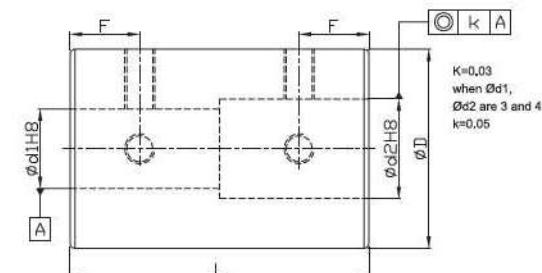
Remark of plastic spacer corresponding to environment temperature.

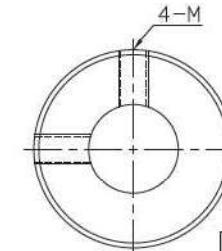
Plastic spacer series include rubber or plastic parts. These model no. must be used in operating temperature range indicated on our catalogs. If temperature over 30°C, max. torque and allowable torque shall be corrected by factors as listed below.

| Environment temperature | Corrective factor |
|-------------------------|-------------------|
| -20°C ~ 30°C | 1.00 |
| 30°C ~ 40°C | 0.80 |
| 40°C ~ 60°C | 0.70 |
| 60°C ~ 100°C | 0.55 |

RAM


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.


 *When $\text{Ød1} < 4$ and $\text{Ød2} > 5$, there would be 3 set screws.

 *When Ød1 and Ød2 both smaller than 4, there would be 2 set screws.


| Material | Surface Finish | Accessories |
|----------------|----------------|-------------|
| Aluminum Alloy | Anodized | Set screw |

| Dimensions | Ød1&Ød2 selection * $\text{Ød1} \leq \text{Ød2}$ | | | | | | | | | | | L | F | M Rough thread | | |
|------------|--|---|---|---|---|----|----|----|----|----|----|----|----|-------------------|------|---|
| | 3 | 4 | 5 | 6 | 8 | 10 | 11 | 12 | 14 | 15 | 16 | 18 | 20 | | | |
| RAM | 16 | * | * | * | * | | | | | | | | | 24 | 6 | 3 |
| | 20 | | * | * | * | * | * | | | | | | | 30 | 7 | |
| | 25 | | | | * | * | * | * | | | | | | 36 | 9 | 4 |
| | 32 | | | | | | | * | * | * | * | | | 41 | 10 | |
| | 40 | | | | | | | | | * | * | * | * | 44 | 10,5 | 5 |

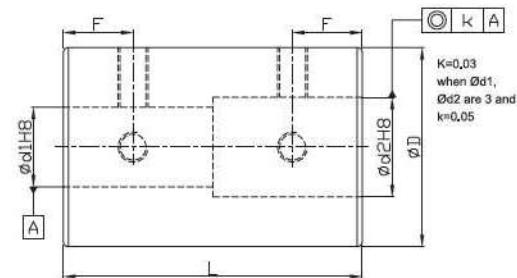
* Moment of inertial torque and weight calculated by maximum diameter.

| Specification | Allowable Wrench Torque (Nm) | Max. RPM (r/min ¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|------------------------------|--------------------------------|--|---------------------------|--------------|
| RAM | 16 | 0.3 | 24000 | 4.4×10^{-7} | 0.7 |
| | 20 | 0.5 | 19000 | 1.3×10^{-6} | |
| | 25 | 1 | 15000 | 3.9×10^{-6} | 1.7 |
| | 32 | 2 | 12000 | 1.2×10^{-5} | |
| | 40 | 4 | 4000 | 1.5×10^{-5} | 4 |
| | | | | | 11 |
| | | | | | 20 |
| | | | | | 39 |
| | | | | | 71 |
| | | | | | 120 |

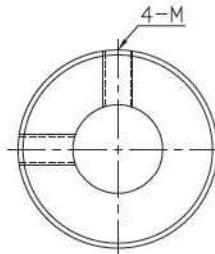
Ordering Example: RAM20 Model no.: 6 Ød1 * 8 Ød2 100 PCS Q'ty

RSM


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.



*When Ød1<4 and Ød2>5, there would be 3 set screws.
*When Ød1 and Ød2 both smaller than 4, there would be 2 set screws.



| Material | Accessories |
|----------|-------------|
| SUS303 | Set screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | | | | | L | F | M Rough thread | |
|------------|----|------------------------------|---|---|---|---|----|----|----|----|----|----|----|----------------------|---|
| Model No. | ØD | 3 | 4 | 5 | 6 | 8 | 10 | 11 | 12 | 14 | 15 | 16 | | | |
| RSM | 16 | • | • | • | • | | | | | | | | 24 | 6 | 3 |
| | 20 | | | • | • | • | • | | | | | | 30 | 7 | |
| | 25 | | | | | • | • | • | • | | | | 36 | 9 | 4 |
| | 32 | | | | | | | • | • | • | • | • | 41 | 10 | |

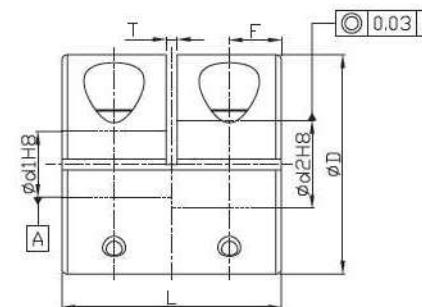
*Moment of inertial torque and weight calculated by maximum diameter.

| Specification | | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|----|-------------------------------|---------------------------------|--|---------------------------|--------------|
| Model No. | ØD | | | | | |
| RSM | 16 | 0.3 | 24000 | 1.2*10 ⁻⁶ | 0.7 | 28 |
| | 20 | 0.5 | 19000 | 3.5*10 ⁻⁶ | | 54 |
| | 25 | 1 | 15000 | 1.0*10 ⁻⁶ | 1.7 | 100 |
| | 32 | 2 | 12000 | 3.1*10 ⁻⁶ | | 190 |

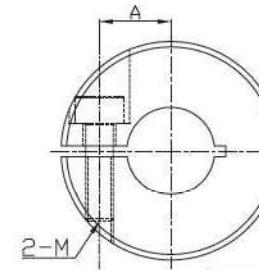
Ordering Example: RSM20 Model no. 8 Ød1 8 Ød2 100 PCS Q'ty

RACS


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.
- Bear type with no allowable offset almost, please show the axis entirely in operating.



*Ød1&Ød2 tolerance are defined before machining.



| Material | Surface Finish | Accessories |
|----------------|----------------|----------------|
| Aluminum alloy | Anodized | Clamping screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | | | | | L | A | T | F | M Rough thread |
|------------|----|------------------------------|---|---|----|----|----|----|----|----|---|----|-----|------|------|----------------------|
| Model No. | ØD | 5 | 6 | 8 | 10 | 12 | 14 | 15 | 16 | 18 | | | | | | |
| RACS | 16 | • | • | | | | | | | | | 16 | 5 | 3.75 | 2.5 | 1 |
| | 20 | | • | • | • | | | | | | | 20 | 6.5 | | | |
| | 25 | | | • | • | • | | | | | | 25 | 9 | | | |
| | 32 | | | | • | • | • | • | | | | 32 | 11 | | | |
| | 40 | | | | | • | • | • | • | • | • | 44 | 13 | 1.5 | 10.5 | 5 |

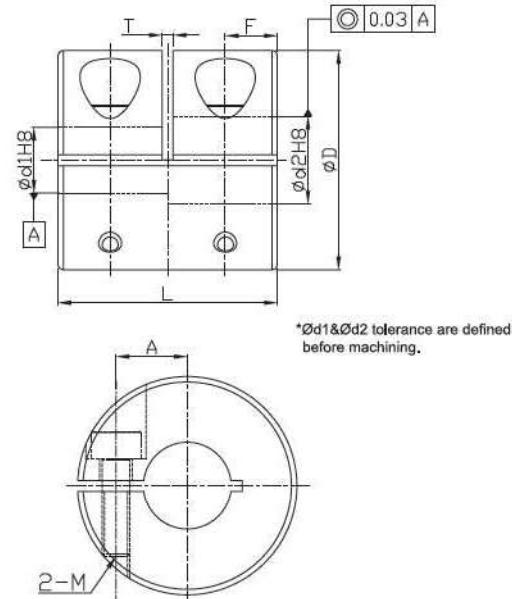
*Moment of inertial torque and weight calculated by maximum diameter.

| Specification | | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|----|-------------------------------|---------------------------------|--|---------------------------|--------------|
| Model No. | ØD | | | | | |
| RACS | 16 | 0.3 | 9500 | 3.0*10 ⁻⁷ | 1 | 9 |
| | 20 | 0.5 | 7600 | 8.7*10 ⁻⁷ | | 15 |
| | 25 | 1 | 6100 | 2.7*10 ⁻⁶ | 1.5 | 29 |
| | 32 | 2 | 4800 | 7.1*10 ⁻⁶ | 2.5 | 61 |
| | 40 | 4 | 4000 | 1.5*10 ⁻⁵ | 7 | 120 |

Ordering Example: RACS32 Model no. 10 Ød1 12 Ød2 100 PCS Q'ty

RSCS


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.
- Beam type with no allowable offset almost, please show the axis entirely in operating.



| Material | Accessories |
|----------|----------------|
| SUS303 | Clamping screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | L | A | T | F | M Rough Thread |
|------------|----|------------------------------|---|---|----|----|----|----|-----|---|------|----------------------|
| Model No. | ØD | 5 | 6 | 8 | 10 | 12 | 14 | | | | | |
| RSCS | 16 | • | • | | | | | 16 | 5 | 1 | 3,75 | 2,5 |
| | 20 | | • | • | | | | 20 | 6,5 | | 4,75 | |
| | 25 | | • | • | | | | 25 | 9 | | 6 | |
| | 32 | | | | • | • | • | 32 | 11 | | 7,75 | |

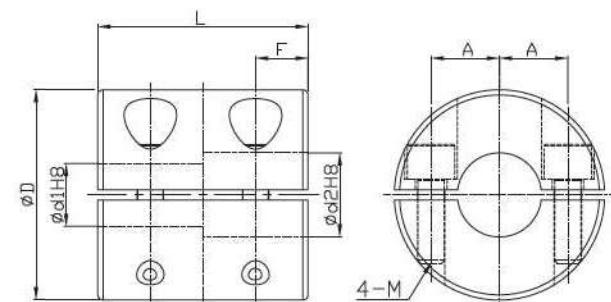
★ Moment of inertial torque and weight calculated by maximum diameter.

| Specification | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|-------------------------------|---------------------------------|--|---------------------------|--------------|
| Model No. | ØD | | | | |
| RSCS | 16 | 0,3 | 9500 | 8,0*10 ⁻⁷ | 1 |
| | 20 | 0,5 | 7600 | 2,4*10 ⁻⁶ | |
| | 25 | 1 | 6100 | 7,3*10 ⁻⁶ | 1,5 |
| | 32 | 2 | 4800 | 2,5*10 ⁻⁵ | 2,5 |

 Ordering Example: RSCS20 - 8 Ød1 - 8 Ød2 - 100 PCS
 Model no. Q'ty

RAB


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.
- Beam type with no allowable offset almost, please show the axis entirely in operating.



| Material | Surface Finish | Accessories |
|----------------|----------------|----------------|
| Aluminum Alloy | Anodized | Clamping screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | L | A | F | M |
|------------|----|------------------------------|---|---|----|----|----|---|---|-----|-----|
| Model No. | ØD | 5 | 6 | 8 | 10 | 12 | 14 | | | | |
| RAB | 16 | • | • | | | | | 1 | 4 | 2,5 | 2,5 |
| | 20 | | • | • | | | | | | | |
| | 25 | | • | • | | | | | | | |
| | 32 | | | | • | • | • | | | | |

★ Moment of inertial torque and weight calculated by maximum diameter.

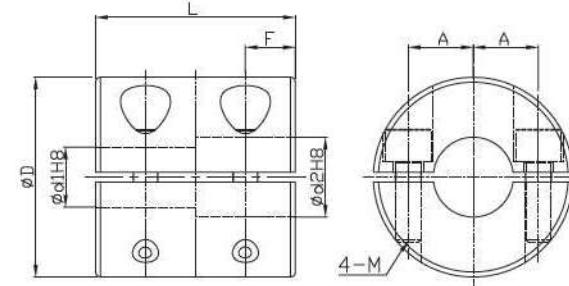
| Specification | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|-------------------------------|---------------------------------|--|---------------------------|--------------|
| Model No. | ØD | | | | |
| RAB | 16 | 0,3 | 9500 | 3,2*10 ⁻⁷ | 1 |
| | 20 | 0,5 | 7600 | 8,7*10 ⁻⁷ | |
| | 25 | 1 | 6100 | 2,7*10 ⁻⁶ | 1,5 |
| | 32 | 2 | 4800 | 9,3*10 ⁻⁶ | 2,5 |

 Ordering Example: RAB25 - 8 Ød1 - 10 Ød2 - 100 PCS
 Model no. Q'ty

Rigidity Coupling

RSB


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.
- Beam type with no allowable offset almost, please show the axis entirely in operating.



*Ød1&Ød2 tolerance are defined before machining.

| Material | Accessories |
|----------|----------------|
| SUS303 | Clamping screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | L | A | F | M |
|------------|----|------------------------------|---|---|----|----|----|----|-----|---|-----|
| Model No. | ØD | 5 | 6 | 8 | 10 | 12 | 14 | | | | |
| RSB | 16 | • | • | | | | | 16 | 5 | 4 | 2.5 |
| | 20 | | • | • | | | | 20 | 6.5 | 5 | |
| | 25 | | | • | • | | | 25 | 9 | 6 | 3 |
| | 32 | | | | • | • | • | 32 | 11 | 8 | 4 |

* Moment of inertial torque and weight calculated by maximum diameter.

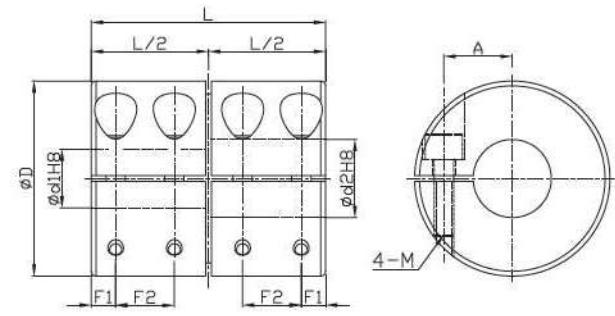
| Specification | | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|----|-------------------------------|---------------------------------|--|---------------------------|--------------|
| Model No. | ØD | | | | | |
| RSB | 16 | 0.3 | 9500 | 8,2*10 ⁻⁷ | 1 | 22 |
| | 20 | 0.5 | 7600 | 2,4*10 ⁻⁶ | | 41 |
| | 25 | 1 | 6100 | 7,3*10 ⁻⁶ | 1.5 | 80 |
| | 32 | 2 | 4800 | 2,5*10 ⁻⁶ | 2.5 | 160 |

Ordering Example: RSB20 - 6 Ød1 - 8 Ød2 - 100 PCS
Model no. Q'ty

Rigidity Coupling

RACL


- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.
- Beam type with no allowable offset almost, please show the axis entirely in operating.



*Ød1&Ød2 tolerance are defined before machining.

| Material | Surface Finish | Accessories |
|----------------|----------------|----------------|
| Aluminum Alloy | Anodized | Clamping screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | L | A | F1 | F2 | M |
|------------|----|------------------------------|---|---|----|----|----|----|----|-----|-----|-----|
| Model No. | ØD | 5 | 6 | 8 | 10 | 12 | 14 | | | | | |
| RACL | 16 | • | • | | | | | 22 | 5 | 5.5 | 2.5 | 2 |
| | 20 | | • | • | | | | 24 | 7 | | | |
| | 25 | | | • | • | | | 36 | 9 | 4.5 | 9 | 2.5 |
| | 32 | | | | • | • | • | 40 | 11 | 4 | 10 | 3 |

* Moment of inertial torque and weight calculated by maximum diameter.

| Specification | | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) |
|---------------|----|-------------------------------|---------------------------------|--|---------------------------|--------------|
| Model No. | ØD | | | | | |
| RACL | 16 | 0,3 | 9000 | 3,4*10 ⁻⁷ | 0,5 | 10 |
| | 20 | 0,5 | 7000 | 9,2*10 ⁻⁷ | | 18 |
| | 25 | 1 | 6000 | 3,4*10 ⁻⁶ | 1 | 38 |
| | 32 | 2 | 4500 | 1,0*10 ⁻⁶ | 1,5 | 70 |

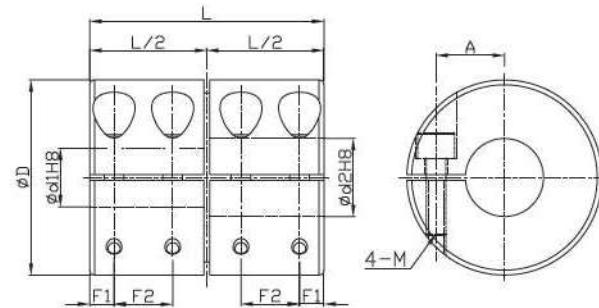
Ordering Example: RACL25 - 8 Ød1 - 10 Ød2 - 100 PCS
Model no. Q'ty

Rigidity Coupling

RSCL



- Light, very low inertial and high sensibility.
- Maintenance free, super anti-oil and corrosion-resistance.
- Beam type with no allowable offset almost, please show the axis entirely in operating.



*Ød1&Ød2 tolerance are defined before machining.

| Material | Accessories |
|----------|----------------|
| SUS303 | Clamping screw |

| Dimensions | | Ød1&Ød2 selection *Ød1 ≤ Ød2 | | | | | | L | A | F1 | F2 | M |
|------------|----|------------------------------|---|---|----|----|----|----|----|-----|-----|-----|
| Model No. | ØD | 5 | 6 | 8 | 10 | 12 | 14 | | | | | |
| RSCL | 16 | • | • | | | | | 22 | 5 | 2,5 | 5,5 | 2 |
| | 20 | | • | • | | | | 24 | 7 | | 6 | |
| | 25 | | | • | • | | | 36 | 9 | 4,5 | 9 | 2,5 |
| | 32 | | | | • | • | • | 40 | 11 | 4 | 10 | 3 |

* Moment of inertial torque and weight calculated by maximum diameter.

| Specification | Allowable Wrench Torque (N·m) | Max. RPM (r/min ⁻¹) | * Moment of Inertia (kg·m ²) | Screw Fixing Torque (N·m) | * Weight (g) | |
|---------------|-------------------------------|---------------------------------|--|---------------------------|--------------|-----|
| Model No. | ØD | | | | | |
| RSCL | 16 | 0.3 | 9000 | 8,9*10 ⁻⁷ | 0.5 | 25 |
| | 20 | 0.5 | 7000 | 2.5*10 ⁻⁶ | | 45 |
| | 25 | 1 | 6000 | 9.2*10 ⁻⁶ | 1 | 100 |
| | 32 | 2 | 4500 | 2.7*10 ⁻⁵ | 1.5 | 180 |

Ordering Example: RSCL25 - 8 Ød1 - 10 Ød2 - 100 Q'ty

Installation Notice :

- (1) To avoid mistakenly operating driver, please be sure to cut off main power and start installation after security confirmation.
- (2) Please clear out miscellaneous, dust and oil...etc attached on the shafts and inner of coupling. Especially for the grease with molybdenum disulfide and extreme pressure additive which affect friction factor substantially, please proceed defatting treatment entirely.
- (3) In order to perform coupling functions completely, please proceed installing as range of max. allowable offset in the spec list. Installation error in the list is top value occurring individually, so please take below half of allowed values in multiple cases into account.
- (4) Please take the ruler against to outer body while centering, with around 90° to proceed checking two departed points. Centering accuracy has huge affection to life hours of unit.
- (5) Please set safety cover after installing this product. Otherwise, it might get hurt by touching products in operating.
- (6) To lock screw, please be sure to use corrected torque wrench and refer to the torque value of clamping lock screw in the spec list to secure.
- (7) Installing by using wrong connecting ways would cause too much vibration, abnormal running or inaccurate center, overloaded deflection to damage motor, coupling...etc mechanism units. It's recommended to notice accuracy balance correction to extend unit life while assembling mechanically.

Operation Notice :

- (1) Considering safety, please set protective jacket on the turning parts of device surrounding couplings.
- (2) If allowable offset is set over limited range or too much torque, it might cause distortion of coupling possible to shorten life.
- (3) If any noise (metal sound) in running, please stop operating, and check any interference to centering and shafts, and screw loosened or not.
- (4) If load variation of device is too much, please put adhesive or adjust one level higher of coupling model to avoid screw loose.

Safety Notice :

In order to work safely, please read description as below, and keep the instruction to recheck the points if necessary.

 **Danger**

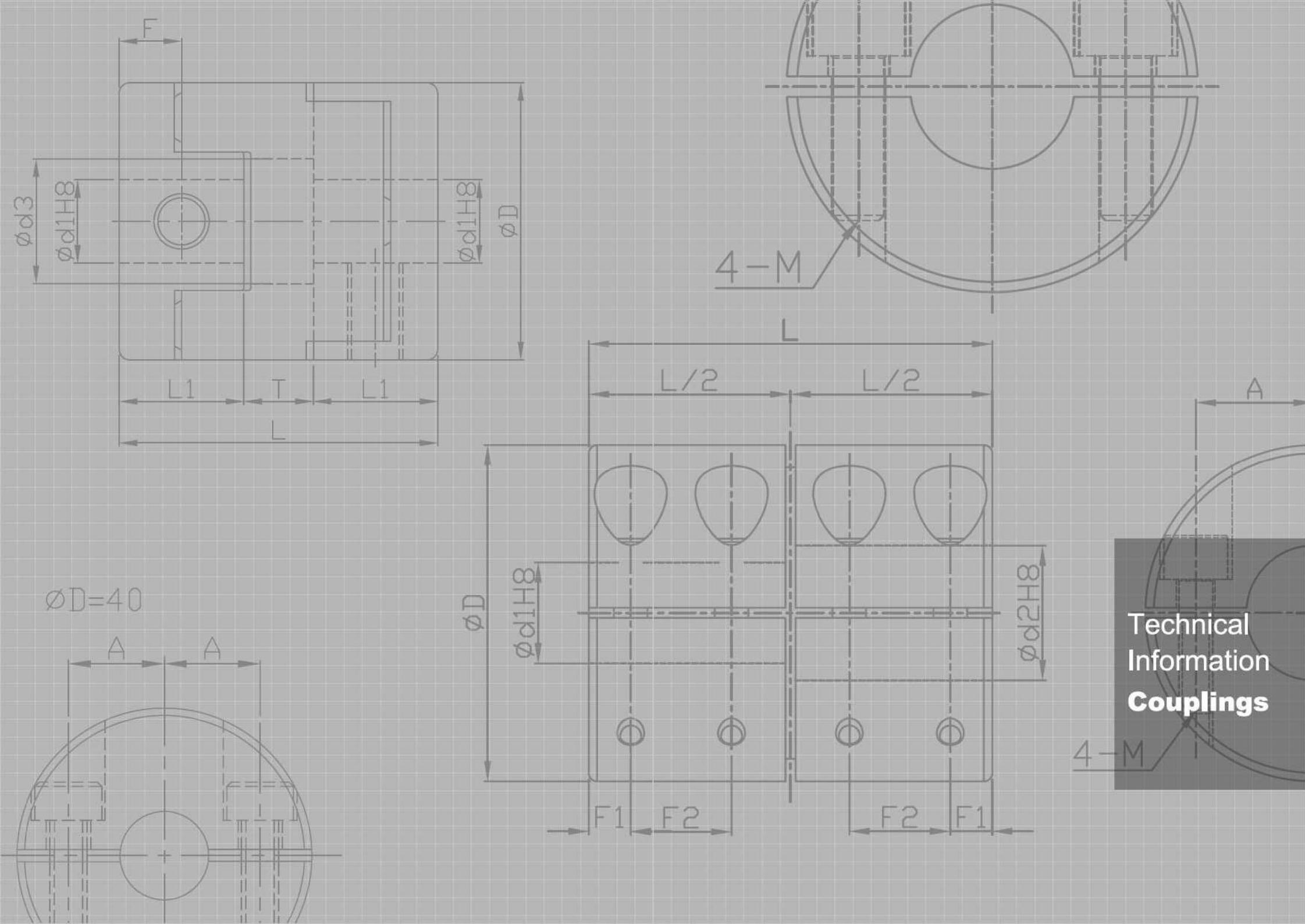
Following acts might cause danger or harmful damage if using mistakenly.

- ◆ For safety work, coupling and related rotating parts must be protected by covers. You might be hurt if touching these parts in operating.
- ◆ To avoid danger, protection device must be installed.
- ◆ Power off is necessary while assembling and disassembling.
- ◆ Lock screw and counter bore screw must be secured by using screwdriver, wrench or torque wrench fitly.
- ◆ Operating speed of product never over top speed.
- ◆ No disassembling or recombinating products.

 **Warning**

Following acts might cause body hurt or wealth loss if using mistakenly.

- ◆ Please operate in allowable deviation range. It might cause damage of coupling if deviation is out of allowed range and probably affect coupling system badly.
- ◆ Torque produced by continuously operating can't exceed rated torque. Otherwise, coupling might be damaged, or affect coupling system badly.
- ◆ While securing, please use screws (lock screw and counter bore screw) appointed by GMT, not any ones else.
- ◆ No operating in the environment affecting products badly.
- ◆ Please stop operation of rotating machine if hearing abnormal noise. Check deviation of machine, any interference between shafts, screws loosened or not...etc.
- ◆ If the rotating machine you use operates in bigger load variation, please use anti-loosen glue on screws to avoid coming off, or use one-size larger coupling.
- ◆ Please ask experts to deal with these products to avoid damage to environment while product abandon.
- ◆ Never touch coupling after completing operation. You might be burned by high temperature caused by coupling system.



Coupling Testing Facility

♦ Exclusive use for coupling test

- (1) For use durability test.
- (2) For mass production inspection in development process.

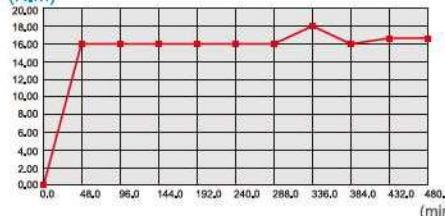
| Coupling Test Report Test Item : General Test | | Tester | Q013 |
|---|------------------------|------------------------|---------------------|
| Model Number : FACE | Type of space ring : R | Test Day | 2012/02/13 16:43:47 |
| Outer diameter : 40 | Inner diameter d1 : 10 | Inner diameter d2 : 10 | |
| Test Parameter | | | |
| Deflection : -1.08° Eccentricity : -0.10 mm | | | |
| Planned testing time : 480 min 0 sec | | | |
| Forward rotation : 0 min 10 sec | | | |
| Pause : 2 sec | | | |
| Inverse rotation : 0 min 10 sec | | | |
| Present torque : 16.50 (N.m) | | | |
| Zeroed torque : 0.00 (N.m) | | | |
| Machine operating time : 480 min 0 sec | | Serial NO. | 20120213-FACE40R-8 |
| Revolution Test : 200 rpm / min | | Back to main page | Back to last page |
| | | Print | |
| | | STOP | |



Tester

Q013

(N.m)



(min)

Remark:

